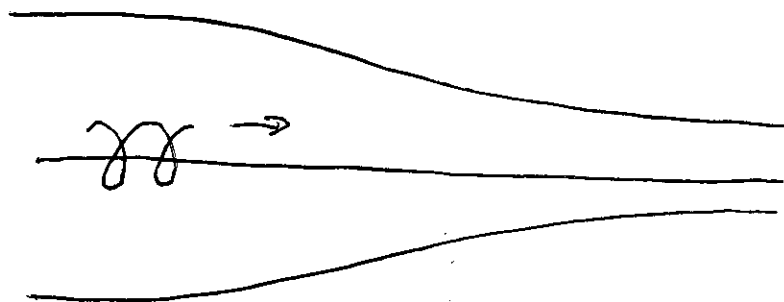


VIII 1

Particle spirals along field which is getting stronger or weaker



If field is static, ^{+ no \vec{E}} then energy is conserved

$$\frac{dU}{dt} = q \vec{E} \cdot \vec{v} = 0 \Rightarrow U = \text{const}$$

$$\Rightarrow \gamma = \text{const} \Rightarrow \boxed{v^2 = v_{\parallel}^2 + v_{\perp}^2 = \text{const}}$$

Also, if change is slow (many cycles over time for field to change) then there is an adiabatic invariant

$$= \begin{cases} B a^2 & \text{flux threading particle orbit} \\ \omega_B a^2 & \\ v_{\perp}^2 / \omega_B & \text{or } v_{\perp}^2 / B \end{cases} \quad \omega_B = \frac{qB}{\gamma mc}$$

i.e. $\frac{v_{\perp}^2}{B(z)} = \frac{v_{\perp 0}^2}{B_0}$

and we have $v_0^2 = v_{\parallel}^2 + v_{\perp 0}^2 \frac{B(z)}{B_0}$

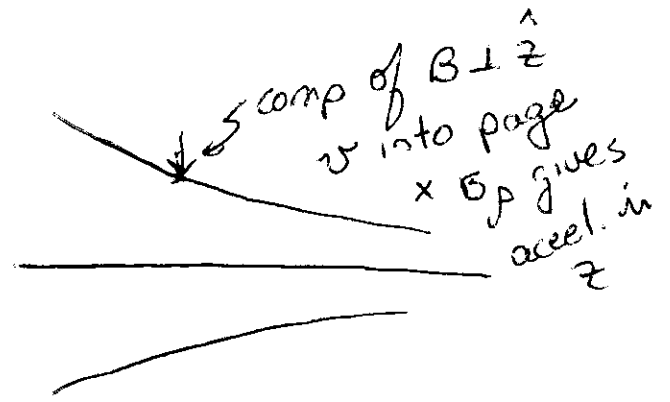
v_0^2 defined as $v^2 = \text{const}$

constants defined so that $v_{\parallel} = 0$ for $z = z_0$, $B(z_0) = B_0$

Problem reduces to that of motion of single particle in 1D potential $\propto B(z)$

z_0 is a turning point

In terms of Lorentz force



Lets use cylindrical coordinates centered on VIII 3a
central line of \vec{B}

$$\vec{B} = \vec{B}(\rho, z) \quad + \quad \text{in } \rho-z \text{ plane}$$

Along z -axis $\vec{B}(\rho, z) = B(z) \hat{z}$

Near z -axis $\vec{\nabla} \cdot \vec{B} = 0$ implies $\frac{1}{\rho} \frac{\partial}{\partial \rho} \rho B_{\rho}(\rho, z) = -\frac{dB}{dz}$

so $B_{\rho} = -\frac{1}{2} \rho \frac{dB}{dz}$

\vec{B} static so γ is constant

$$\ddot{\rho} - \rho \dot{\phi}^2 = \frac{q}{\gamma mc} (\vec{v} \times \vec{B})_{\rho}$$

$$\rho \ddot{\phi} + 2\dot{\rho}\dot{\phi} = \frac{q}{\gamma mc} (\vec{v} \times \vec{B})_{\phi}$$

$$\ddot{z} = \frac{q}{\gamma mc} (\vec{v} \times \vec{B})_z$$

0th order $\rho = a$ + first equation gives

$$-\rho \dot{\phi}^2 = \frac{q}{\gamma m c} \rho \dot{\phi} B_z \quad \text{or} \quad \dot{\phi} = -\frac{qB}{\gamma m c} \quad \checkmark$$

as well, second gives $\rho^2 \dot{\phi} = \text{const.}$

positive ω_B
implies
neg. $\dot{\phi}$

$$= -a^2 \omega_{B,0} = -\frac{v_{\perp 0}^2}{\omega_{B,0} \rho}$$

$$\omega_{B,0} = \frac{qB}{\gamma m c}$$

At 0th order $\ddot{z} = 0$ but small B_ρ cross v_ϕ

implies z force.

$$\ddot{z} = \frac{q}{2\gamma m c} \rho^2 \dot{\phi} \frac{dB}{dz}$$

$$\approx -\frac{v_{\perp 0}^2}{2} \frac{q}{\gamma m c} \frac{1}{\omega_{B,0}} \frac{dB}{dz} = -\frac{v_{\perp 0}^2}{2B_0} \frac{dB}{dz}$$

$$\text{so} \quad \frac{1}{2} \dot{z}^2 + \frac{v_{\perp 0}^2}{2} \frac{B(z)}{B_0} = \frac{v_0^2}{2} \quad \text{integration const.}$$

Lagrangian mechanics

non relativistic formalism

$$L = L(q_i, \dot{q}_i, t)$$

$$A = \int_{t_1}^{t_2} L dt$$

A an extremum $\delta A = 0$

$$\delta A = \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q_i} \delta q_i + \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i \right) dt$$

$$\frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \delta q_i \right) - \delta q_i \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i}$$

$$\text{so } \delta A = \int_{t_1}^{t_2} \left(\left(\frac{\partial L}{\partial q_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} \right) \delta q_i + \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \delta q_i \right) \right) dt$$

$$\Rightarrow \frac{\partial L}{\partial q_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = 0$$

NR case $L = K - V = \frac{1}{2}m\vec{v}^2 - V(\vec{x})$

gives $-\vec{\nabla}V - \frac{d}{dt}m\vec{v} = 0$ or $\vec{F} = m\vec{a}$

Now A should be a Lorentz invariant scalar

$$A = \int_{t_1}^{t_2} L dt = \int_{\tau_1}^{\tau_2} L \frac{dt}{d\tau} d\tau$$
 τ proper time
$$= \int_{\tau_1}^{\tau_2} \gamma L d\tau$$

so γL must be a Lorentz invariant scalar

for a free particle, only 4-vector is u^α , only scalar is $u^\alpha u_\alpha = -c^2$

$$L_{free} = -\frac{mc^2}{\gamma} = -mc^2 \left(1 - \frac{v^2}{c^2}\right)^{1/2}$$

$$\approx -mc^2 + \frac{1}{2}m\vec{v}^2$$
 NR limit

$$\frac{\partial L}{\partial q_i} = 0 \Rightarrow \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = \frac{d}{dt} \left(\frac{m\dot{v}_i}{\left(1 - v^2/c^2\right)^{1/2}} \right) = \frac{d}{dt} \gamma m \dot{v}_i = 0$$

i.e. $p_i = \text{const.}$

Now we include interactions

VIII 6

NR Lagrangian - $K - V$ $V = e\Phi$

i.e. $L_{int} = -e\Phi$

less obvious what to do with Lorentz force.

Use relativity. For particle at rest $u^\alpha = (c, 0)$; $A^\alpha = (\Phi, \vec{A})$
covariant ∇

so $L_{int} = -\frac{e}{\gamma c} u^\alpha A_\alpha$ then δL_{int} is Lorentz invariant
scalar + $L_{int} \approx -e\Phi$ for
particle initially at rest.

$$= -e\Phi + \frac{e}{c} \vec{v} \cdot \vec{A}$$

so the Lagrangian for the Lorentz force is $\frac{e}{c} \vec{v} \cdot \vec{A}$

$$L = -mc^2 \left(1 - \frac{v^2}{c^2}\right)^{1/2} + \frac{e}{c} \vec{v} \cdot \vec{A} - e\Phi$$

variation gives $\frac{d}{dt} \gamma m \vec{v} = e \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$

where $\vec{E} = -\vec{\nabla}\Phi - \frac{\partial \vec{A}}{\partial t}$ $\vec{B} = \vec{\nabla} \times \vec{A}$ and $\frac{d}{dt} = \frac{\partial}{\partial t} + \frac{d\vec{x}}{dt} \cdot \frac{\partial}{\partial \vec{x}}$
 $= \frac{\partial}{\partial t} + \vec{v} \cdot \vec{\nabla}$

Canonical momentum \vec{P} conjugate to position \vec{x} VIII 7

$$P_i = \frac{\partial L}{\partial v_i} = \gamma m v_i + \frac{e}{c} A_i = p_i + \frac{e}{c} A_i$$

conjugate momentum is the conserved quantity if L is independent of the associated coordinate

ordinary (relativistic) momentum

Hamiltonian $H = \vec{P} \cdot \vec{v} - L$

now $\gamma m \vec{v} = \vec{P} - \frac{e}{c} \vec{A}$

$$\frac{v^2}{1-v^2/c^2} = \left(\frac{\vec{P} - \frac{e}{c} \vec{A}}{m} \right)^2$$

solve for v^2 or γ

$$\frac{v^2}{c^2} = \frac{\left(\vec{P} - \frac{e}{c} \vec{A} \right)^2}{\left(\left(\vec{P} - \frac{e}{c} \vec{A} \right)^2 + m^2 c^2 \right)^{1/2}}$$

$$\vec{v} = \frac{c \vec{P} - e \vec{A}}{\left(\left(\vec{P} - \frac{e}{c} \vec{A} \right)^2 + m^2 c^2 \right)^{1/2}}$$

$$H = \left((c\vec{P} - e\vec{A})^2 + m^2 c^4 \right)^{1/2} + e\Phi$$

i.e. $\vec{P} \cdot \vec{v} + mc(1-v^2/c^2)^{1/2} - \frac{e}{c} \vec{v} \cdot \vec{A} + e\Phi$

H gives the total energy W of the particle
 $U + e\Phi$ where U is kinetic energy
 (conserved if fields are time independent)

$$(W - e\Phi)^2 = (c\vec{P} - e\vec{A})^2 + (mc^2)^2$$

So p^α usual 4-momentum of particle

$$p_\alpha p^\alpha = (mc)^2 \quad \text{Lorentz invariant}$$

$$E^2 = (pc)^2 + (mc^2)^2$$

$$P^\alpha = p^\alpha + \frac{e}{c} A^\alpha$$

$$= \left(\frac{E}{c} + \frac{e}{c} \Phi, \vec{p} + \frac{e}{c} \vec{A} \right)$$

canonical conjugate 4-momentum

i.e. $p^0 = \frac{E}{c} + \frac{e\Phi}{c}$ zeroth comp. of canonical momentum

$$H = \left((c\vec{P} - e\vec{A})^2 + m^2c^4 \right)^{1/2} + e\Phi$$

Hamiltonian.

Derive Lorentz force from Hamilton's equations

$$-\frac{\partial H}{\partial x_i} = \frac{dP^i}{dt} \qquad \frac{\partial H}{\partial P_i} = \frac{dx^i}{dt}$$

↓
gives

$$\vec{v} = \frac{c\vec{P} - e\vec{A}}{\left((c\vec{P} - e\vec{A})^2 + m^2c^4 \right)^{1/2}} \checkmark$$

NR limit

$$H = mc^2 + \frac{1}{2m} \left(\vec{P} - \frac{e}{c}\vec{A} \right)^2 + e\Phi$$

$$= mc^2 + \frac{(\vec{P})^2}{2m} - \frac{e}{mc} \vec{P} \cdot \vec{A} + \frac{e^2}{2mc^2} A^2 + e\Phi$$

Particle in uniform field \vec{B}

$$\vec{A} = -\frac{1}{2} \vec{r} \times \vec{B}$$

$$\vec{\nabla} \times \vec{A} = -\frac{1}{2} \vec{\nabla} \times (\vec{r} \times \vec{B})$$

$$= \frac{1}{2} \left(\vec{B} (\underbrace{\vec{\nabla} \cdot \vec{r}}_{=3}) - (\underbrace{\vec{B} \cdot \vec{\nabla}}_{=\vec{B}}) \vec{r} \right) = \vec{B} \checkmark$$

$$-\frac{e}{mc} \vec{p} \cdot \vec{A} = \frac{e}{2mc} \vec{p} \cdot (\vec{r} \times \vec{B}) = \frac{e}{2mc} \vec{B} \cdot (\vec{p} \times \vec{r})$$

$$= -\frac{e}{2mc} \vec{B} \cdot \vec{L}$$

Covariant treatment

Twin paradox - free particle follows path of maximal proper time

$$A \propto \int_{\tau_1}^{\tau_2} d\tau$$

$$cd\tau = \left(\eta_{\alpha\beta} dx^\alpha dx^\beta \right)^{1/2} = \left(\eta_{\alpha\beta} \frac{dx^\alpha}{ds} \frac{dx^\beta}{ds} \right)^{1/2} ds$$

$$A = -mc \int_{\tau_1}^{\tau_2} \left(\eta_{\alpha\beta} \frac{dx^\alpha}{ds} \frac{dx^\beta}{ds} \right)^{1/2} ds$$

s is any ^{monotonic} parameter along path
units of ang. momentum
same as \hbar

$$L_{\text{free}} = -mc \left(\eta_{\alpha\beta} \frac{dx^\alpha}{ds} \frac{dx^\beta}{ds} \right)^{1/2}$$

Euler-Lagrange

$$\frac{d}{ds} \frac{\partial L}{\partial \frac{dx^\alpha}{ds}} = \frac{\partial L}{\partial x^\alpha}$$

for free particle $\frac{\partial L}{\partial x^\alpha} = 0$ and we have

$$\frac{\partial L}{\partial \frac{dx^\alpha}{ds}} = \text{const.} \quad \text{i.e.} \quad \frac{mc \frac{dx^\alpha}{ds}}{\left(\quad \right)^{1/2}} = 0$$

but $\left(\quad \right)^{1/2} ds = c d\tau$ so $\frac{dx^\alpha}{d\tau} = \text{constant.}$

for charged particle, must add interaction term.

At our disposal $\frac{dx^\alpha}{ds}$ and A^α

$$\begin{aligned} A &= - \int_{s_1}^{s_2} \left[mc \left(\eta_{\alpha\beta} \frac{dx^\alpha}{ds} \frac{dx^\beta}{ds} \right)^{1/2} + \frac{e}{c} \frac{dx^\alpha}{ds} A_\alpha(x) \right] ds \\ &= \int_{s_1}^{s_2} L ds \end{aligned}$$

$$\frac{\partial L}{\partial x^\alpha} = -\frac{e}{c} \frac{dx^\beta}{ds} \frac{\partial A_\beta}{\partial x^\alpha}$$

$$\frac{\partial L}{\partial \frac{dx^\alpha}{ds}} = -mc \frac{\frac{dx_\alpha}{ds}}{\left(\eta_{\beta\gamma} \frac{dx^\beta}{ds} \frac{dx^\gamma}{ds}\right)^{1/2}} - \frac{e}{c} A_\alpha(x)$$

$$= -m \frac{dx_\alpha}{d\tau} - \frac{e}{c} A_\alpha(x)$$

so

$$\frac{d}{d\tau} \left(m \frac{dx^\alpha}{d\tau} + \frac{e}{c} A^\alpha(x) \right) = \frac{e}{c} \frac{dx^\beta}{d\tau} \frac{\partial A_\beta}{\partial x^\alpha}$$

and

$$\frac{d}{d\tau} = \frac{dx^\beta}{d\tau} \frac{\partial}{\partial x^\beta}$$

so

$$m \frac{d^2 x^\alpha}{d\tau^2} + \frac{e}{c} (\partial^\beta A^\alpha - \partial^\alpha A^\beta) \frac{dx^\beta}{d\tau} = 0$$

$$m \frac{d^2 x^\alpha}{d\tau^2} + \frac{e}{c} F^{\alpha\beta} \frac{dx^\beta}{d\tau} = 0 \quad \checkmark$$

Adiabatic invariants

q_i generalize coordinate

p_i conjugate momentum

$$\oint p_i dq_i \approx \text{constant} = J$$

e.g. pendulum with changing length

$$L = \frac{1}{2} ml^2 \dot{\theta}^2 - mgl(1 - \cos\theta)$$

$$\approx \frac{1}{2} ml^2 \dot{\theta}^2 - mgl \frac{\theta^2}{2} \quad \theta = \theta_0 \cos \omega t \quad \omega = \left(\frac{g}{l}\right)^{1/2}$$

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}} = ml^2 \dot{\theta}$$

$$J_\theta = \oint p_\theta dq_\theta = \int_0^T ml^2 \dot{\theta} d\theta = ml^2 \omega \theta_0^2 = ml^{3/2} g^{1/2} \theta_0^2$$

$$\text{So } l^{3/2} \theta_0^2 = \text{const}$$

$$E = ml^2 \dot{\theta}^2 = ml^2 \theta_0^2 \omega^2 \quad \text{so } E/\omega \text{ is approx const.}$$

(though E, ω are not)

$$\mathcal{J} = \oint \vec{P}_\perp \cdot d\vec{l}$$

$$= \oint \gamma m \vec{v}_\perp \cdot d\vec{l} + \frac{e}{c} \oint \vec{A} \cdot d\vec{l}$$

$$d\vec{l} = \vec{v}_\perp dt = \frac{\vec{v}_\perp}{\omega_B} d\phi \quad \frac{v_\perp^2}{\omega_B} = \omega_B a^2$$

$$\oint \vec{A} \cdot d\vec{l} = \int (\vec{\nabla} \times \vec{A}) \cdot \hat{n} dA = \int \vec{B} \cdot \hat{n} dA = B a^2$$

$$\text{But } B = \frac{\gamma m c \omega_B}{e}$$

Also two terms have opposite sign.

$$\mathcal{J} = \frac{e}{c} \pi B a^2 = \gamma m \omega_B a^2 \pi$$