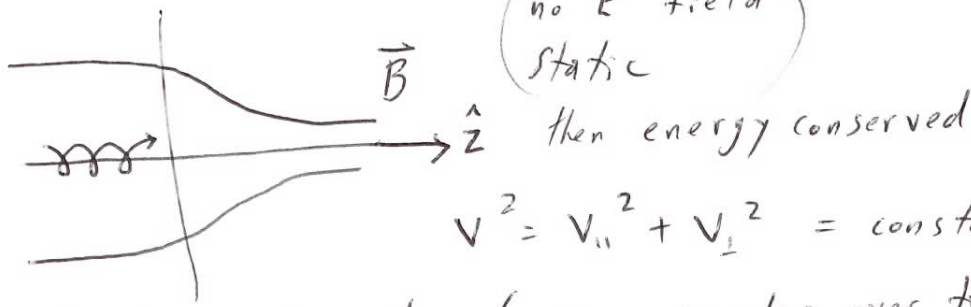


Adiabatic Invariance of Flux (previously $\vec{\nabla} B$ was \perp ; now add \parallel)
 (no \vec{E} field) static

$$\frac{d\text{Energy}}{dt} = q \vec{E} \cdot \vec{v} = 0$$



$$v^2 = v_{\parallel}^2 + v_{\perp}^2 = \text{constant}$$

if change is slow (many cycles over time for field to change)

there is an **adiabatic invariant**

$B a^2$ flux threading particle orbit

or $\omega_B a^2$

since $\omega_B = \frac{qB}{\gamma m}$ (γ is constant)

or $\frac{v_{\perp}^2}{\omega_B}$ or $\frac{v_{\perp}^2}{B}$ (from $v_{\perp} = a \omega_B$)

or $\frac{p_{\perp}^2}{B}$

see Jackson 12.5 for discussion of action integral $\oint p_i dq_i$ over complete cycle of q_i establishing adiabatic invariant

@ $z=0$, axial field B_0 ; $v_{\perp 0}$; $v_{\parallel 0}$; $v_0^2 = v_{\parallel 0}^2 + v_{\perp 0}^2$

$$\frac{v_{\perp}^2}{B} = \frac{v_{\perp 0}^2}{B_0}$$

$$\therefore v_{\parallel}^2 = v_0^2 - v_{\perp}^2 = v_0^2 - \frac{v_{\perp 0}^2}{B} B(z)$$

$v_{\parallel} \rightarrow 0$ when $\dots = 0$ { translational energy converted into rotational energy until $v_{\parallel} = 0$, then reflected

above determined using $\frac{v_{\perp}^2}{B}$ adiabatic invariance

show the same using Lorentz force

use cylindrical coordinates

\vec{B} static so γ is constant

$$\vec{B} = \vec{B}(\rho, z)$$

along z-axis $\vec{B} = B(z) \hat{z}$

near z-axis $\vec{\nabla} \cdot \vec{B} = 0$ implies

$$\frac{1}{\rho} \frac{\partial}{\partial \rho} [\rho B_\rho(\rho, z)] = -\frac{\partial B}{\partial z}$$

$$\therefore B_\rho = -\frac{1}{2} \rho \frac{\partial B}{\partial z}$$

$$\textcircled{1} \quad \ddot{\rho} - \rho \dot{\phi}^2 = \frac{q}{\gamma_m} (\vec{v} \times \vec{B})_\rho$$

$$\textcircled{2} \quad \rho \ddot{\phi} + 2\dot{\rho}\dot{\phi} = \frac{q}{\gamma_m} (\vec{v} \times \vec{B})_\phi$$

$$\textcircled{3} \quad \ddot{z} = \frac{q}{\gamma_m} (\vec{v} \times \vec{B})_z$$

0th order: $\rho = a$ and $\textcircled{1}$ gives $-\rho \dot{\phi}^2 = \frac{q}{\gamma_m} \rho \dot{\phi} B_z$ or $\dot{\phi} = \frac{-qB}{\gamma_m}$

$\textcircled{2}$ gives $\rho^2 \dot{\phi}$ const.

$$= -a^2 \omega_{B,0} = \frac{-v_{\perp 0}^2}{\omega_{B,0}}$$

$$\omega_{B,0} = \frac{qB}{\gamma_m}$$

$\oplus \omega_B$ implies $\ominus \dot{\phi}$

at 0th order $\ddot{z} = 0$ but small $B_\rho \times v_\phi$ implies z force

$$\ddot{z} = \frac{q}{2\gamma_m} \rho^2 \dot{\phi} \frac{\partial B}{\partial z}$$

$$\approx -\frac{v_{\perp 0}^2}{2} \frac{q}{\gamma_m} \frac{1}{\omega_{B,0}} \frac{\partial B}{\partial z} = \frac{-v_{\perp 0}^2}{2B_0} \left(\frac{\partial B}{\partial z} \right)$$

using $\frac{d\dot{z}}{dt} = k \frac{dB}{dz} = k \frac{dB}{dt} \cdot \frac{dt}{dz}$

$$\therefore \int \dot{z} d\dot{z} = \int k dB$$

$$\frac{1}{2} \dot{z}^2 - \frac{1}{2} v_0^2 = -\frac{v_{\perp 0}^2}{2B_0} B(z)$$

and thus

$$\dot{z}^2 = v_0^2 - \frac{v_{\perp 0}^2}{B_0} B(z)$$